

How to best account for crustal deformation in Mayotte?



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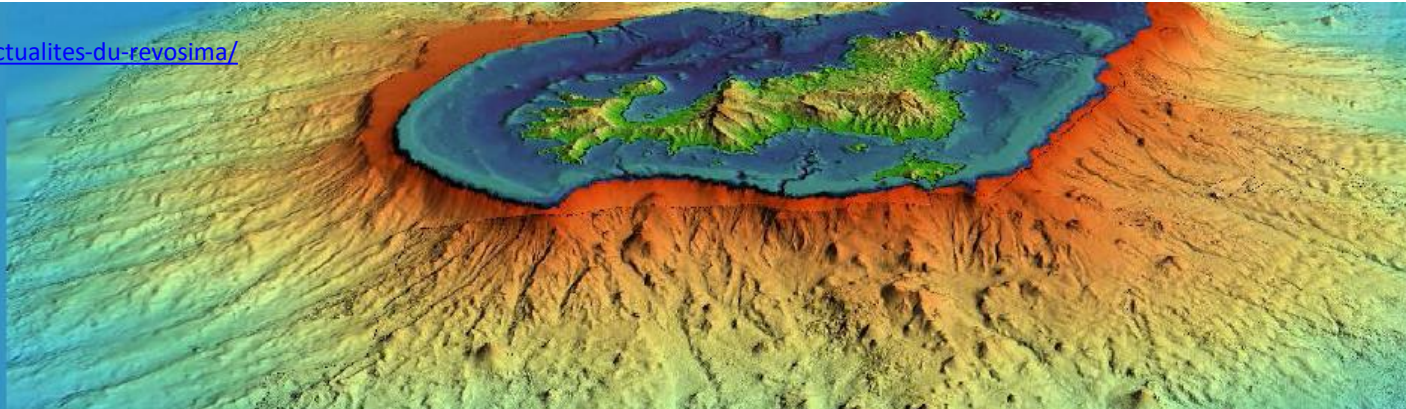


Image source:
<https://www.ipgp.fr/actualites-du-revosima/>

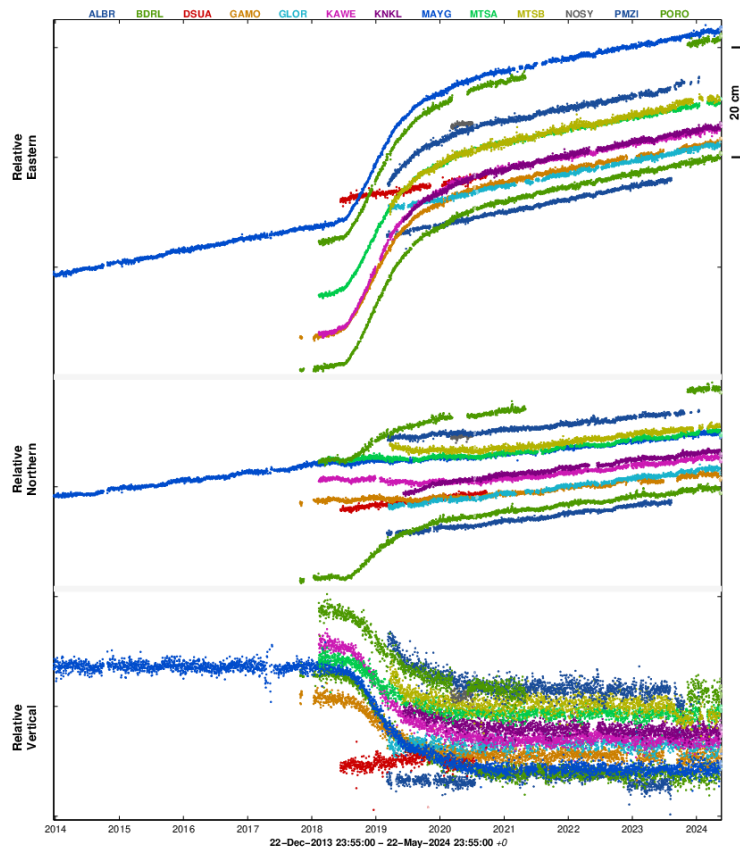
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Acknowledgment: Kristel Chanard, Bruno Garayt, Didier Bouteloup

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GNSS GipsyX REVOSIMA – ITRF2014 (All data)

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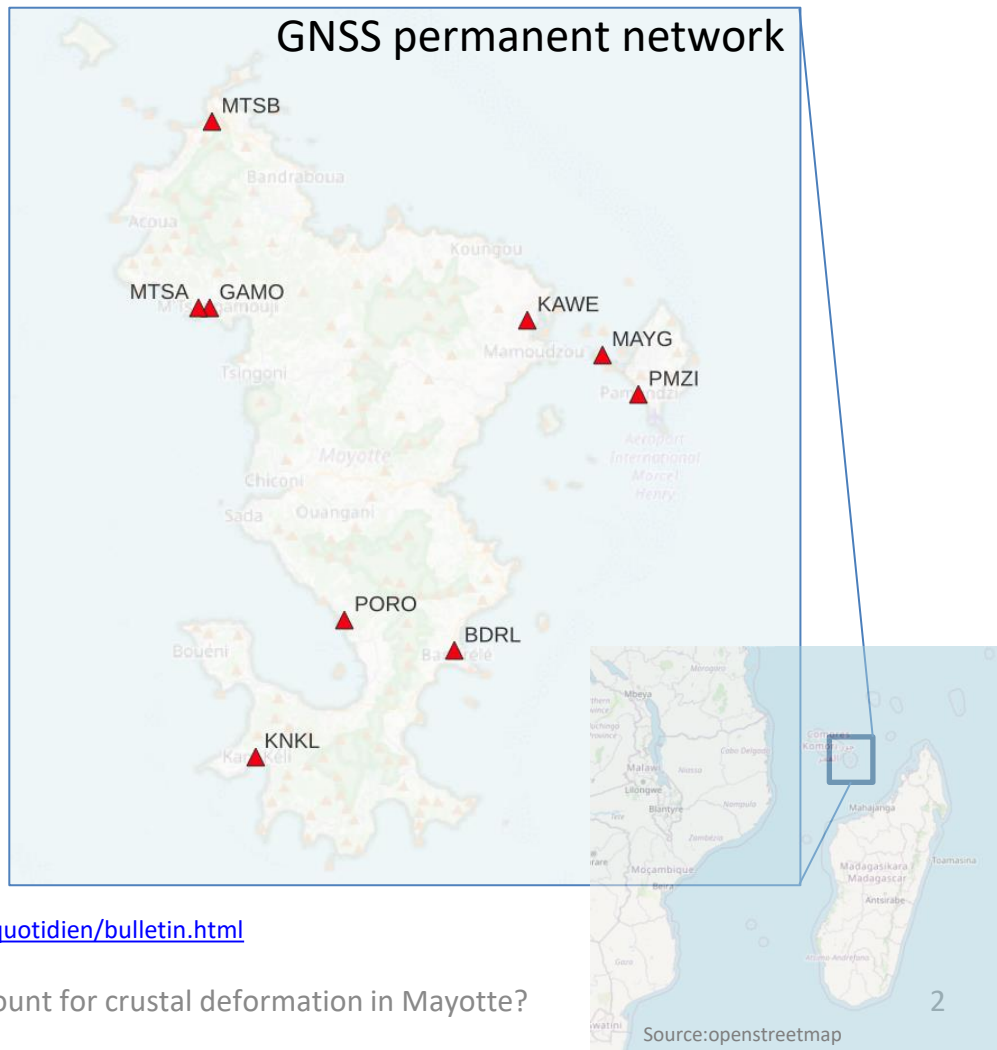
Referential: ITRF2014

E +0 mm/yr
N +0 mm/yr
U +0 mm/yr

Source: https://www.ipgp.fr/volcanoweb/mayotte/Bulletin_quotidien/bulletin.html

PROC.GIPSYX/REVOSIMA / _s1 - xygip@ipg.fr/bondescolumbe - 23-May-2024 08:57:30 +0 - gipsy.xm (2022-10-19) / WebObs MMXXIV

GNSS permanent network

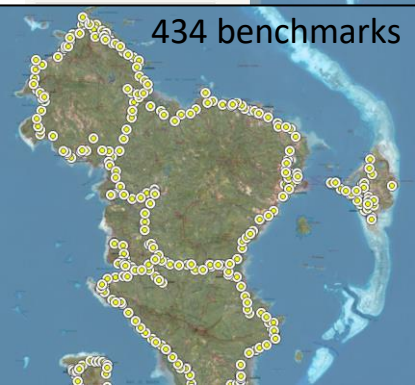
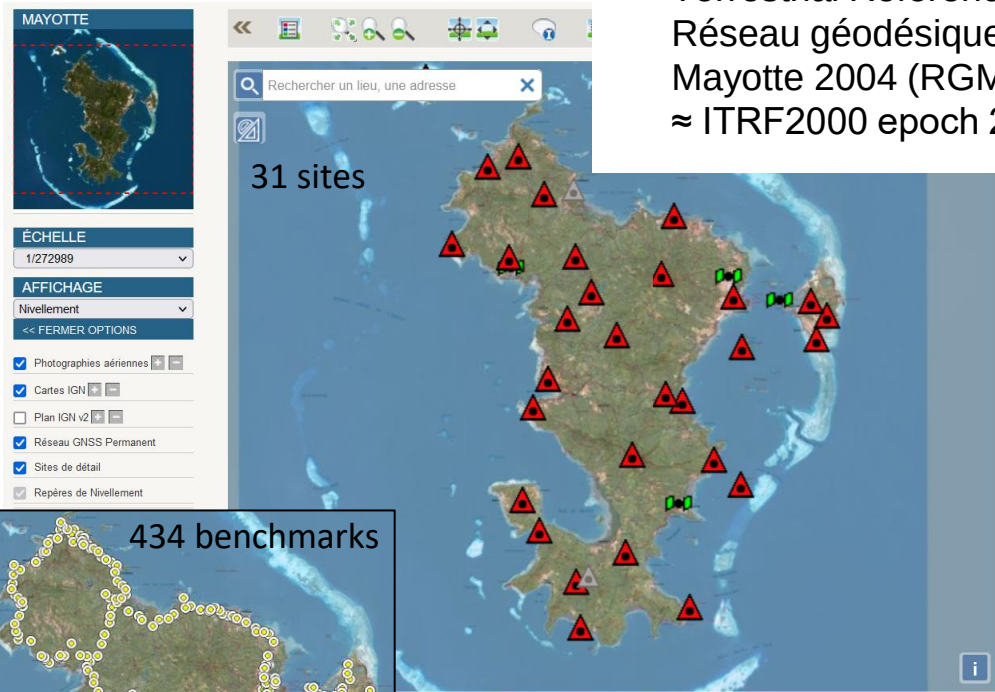


EUREF 2024 - How to best account for crustal deformation in Mayotte?

Reference Frame in Mayotte

- Terrestrial Reference Frame :
Réseau géodésique de Mayotte 2004 (RGM04)
≈ ITRF2000 epoch 2004.0

Given the seismo-volcanic activity, the accuracy of the published coordinates is no longer guaranteed since Mai 2018. See : <https://www.ipgp.fr/actualites-du-revosima>



- Vertical reference system:
IGN 1950 / SHOM 1953 (MAYO53)

IGN Réseau Géodésique Français

COMBANI III

Point : b

Base : Terme Nord 1950

Compte tenu de l'activité sismo-volcanique la précision des coordonnées publiée n'est plus garantie depuis mai 2018. Voir : <https://www.ipgp.fr/actualites-du-revosima/>

Élément de rattachement à votre compte doit être signalé au

Ellipsoïde : IAG GRS

Précision
5 cm
50 cm

Projection : UTM SUD

Altitude (m)	Précision alti
45.60	< 50 cm

Field work by IGNF in autumn 2023:

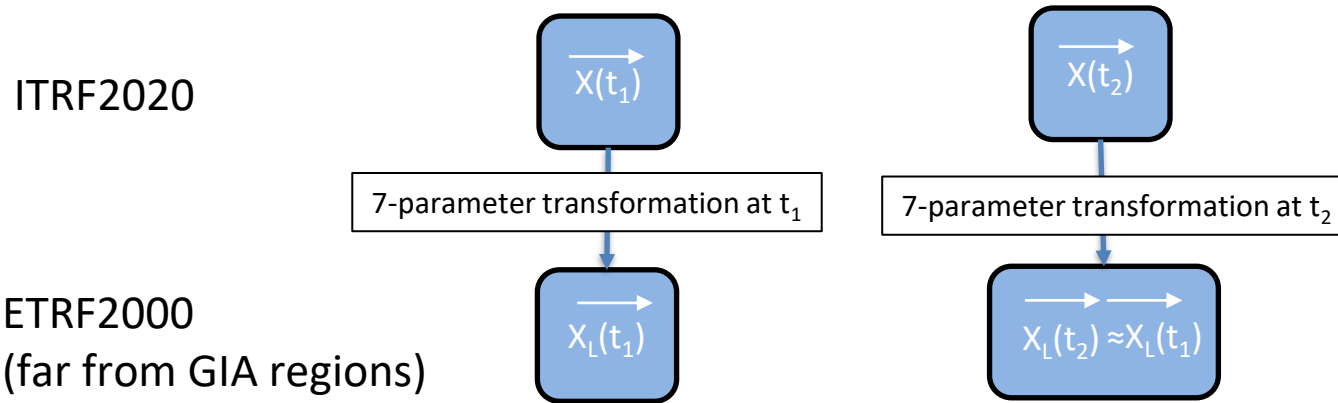
- O GNSS : campaign (static survey)
- O Levelling (about 260 km)
- O gravity measurements : 6 AG points, 6 gradients, relative gravity measurments

Data processing in progress

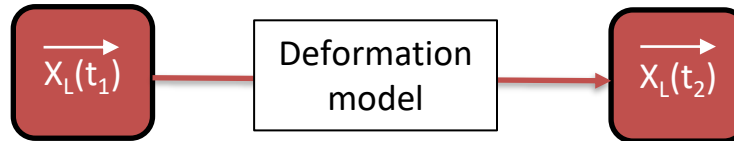
web site.

Deformation model in geodesy

In the stable part of a tectonic plate, a terrestrial reference system which co-rotates with the tectonic plate can be defined. Ex: ETRS89

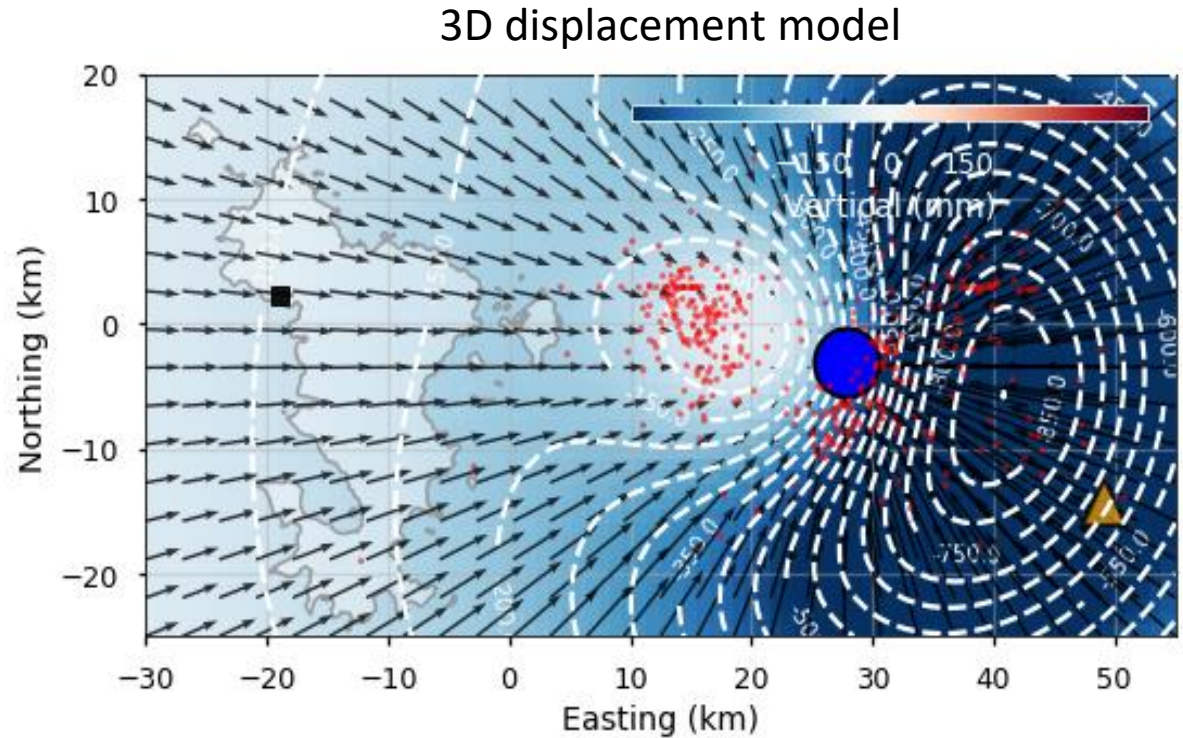


In a deformation zone: $X_L(t_2) \neq X_L(t_1)$



Outline

- Deformation model
- Model evaluation
- Perspectives



Deformation model

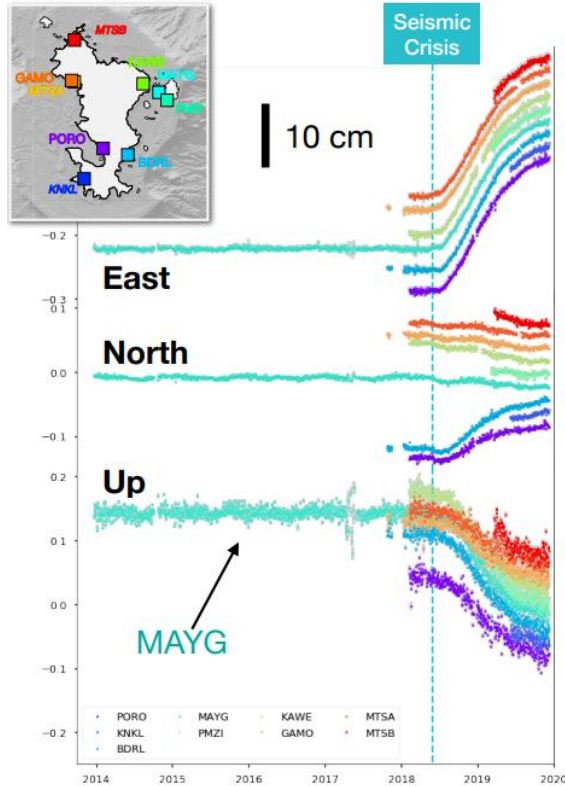


Figure: Used GNSS position time series. Grandin et al. (2019)

Principal component analysis (PCA) of GNSS displacements

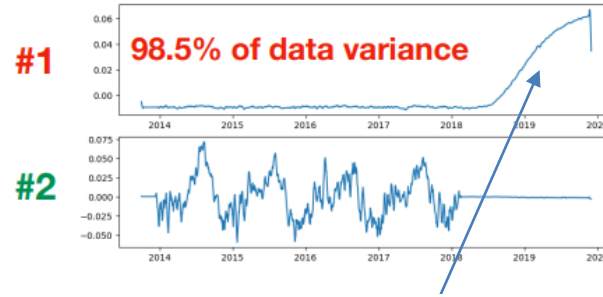


Fig. Two first temporal components

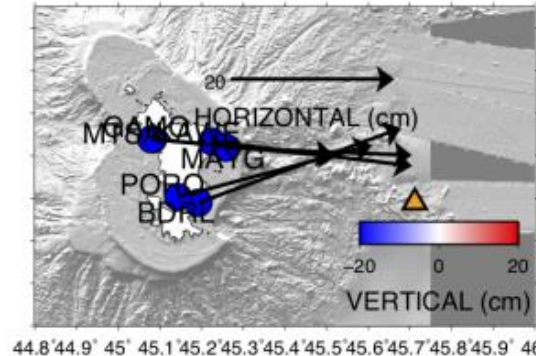


Fig. Spatial component associated to the first temporal component.

Deformation model

Can be explained by a fluid-filled cavity (reservoir) whose outlet is connected to a pipe. The reservoir gradually equilibrates its pressure by expelling material through the pipe. A function that makes use of two exponential functions can model such a behavior (Le Mével et al., 2016)

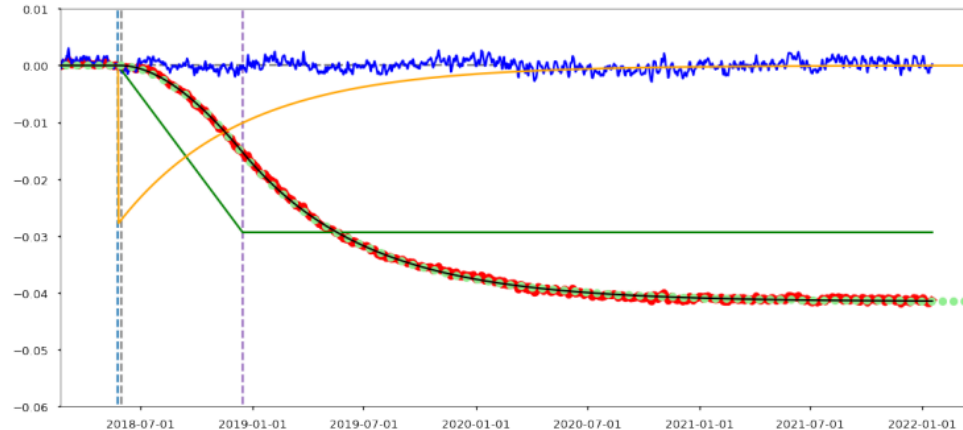
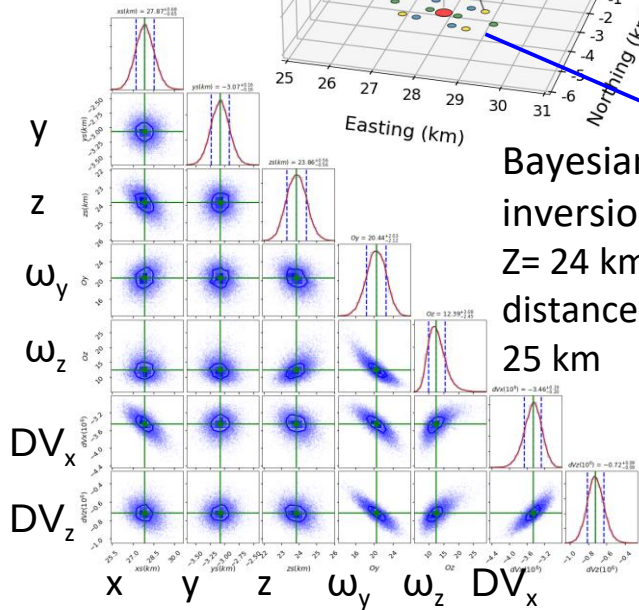
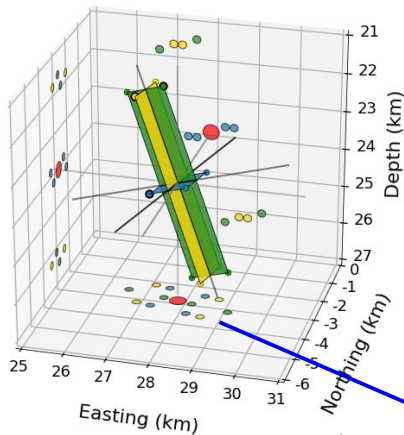


Fig. **Red** : First component of the PCA. **Black**: Estimated model. **Blue** : residuals. **Green** : pressure history imposed at the extremity of the pipe

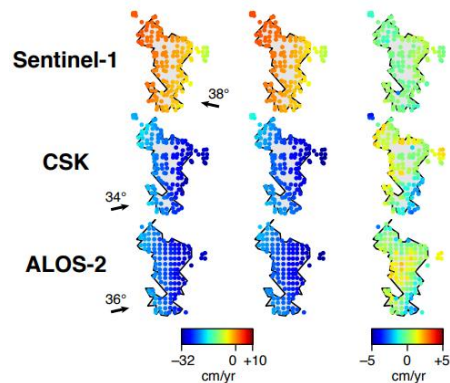
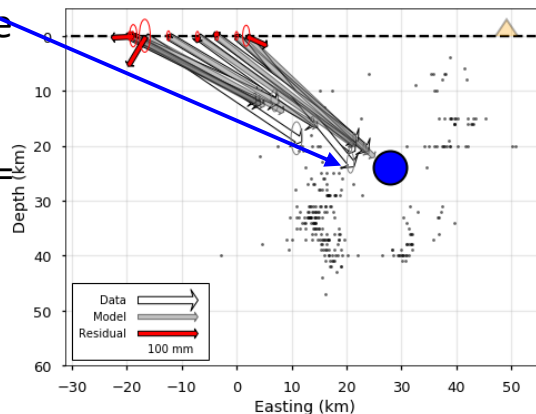
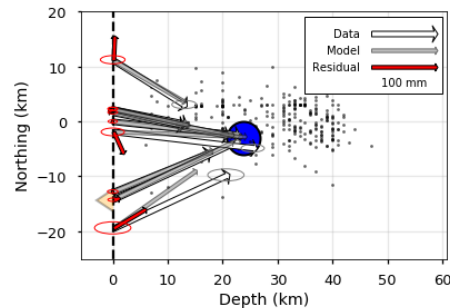
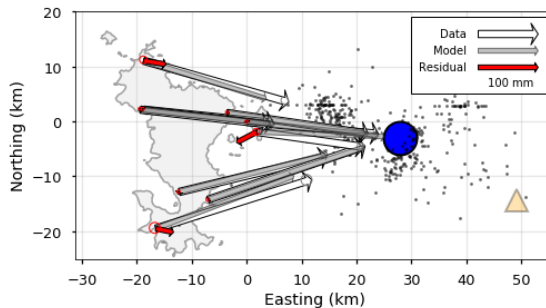
Deformation model

Compound
Dislocation
Model :
«deflating
pipe »
(-5 km³)



Bayesian source
inversion :
Z= 24 km /
distance-MAYG =
25 km

Adjustment of cumulated displacements
(2018–2022) : residuals < 1 cm



Deformation model

➡ Implementation in « proj » library (<https://proj.org>)

Deformation can be represented with such a decomposition

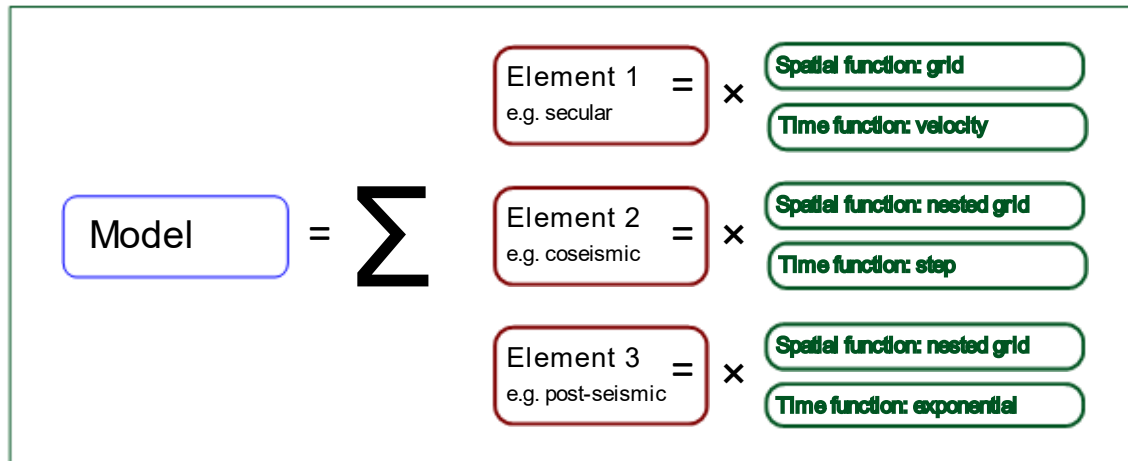


Fig. Adapted from Crook C. (2019)

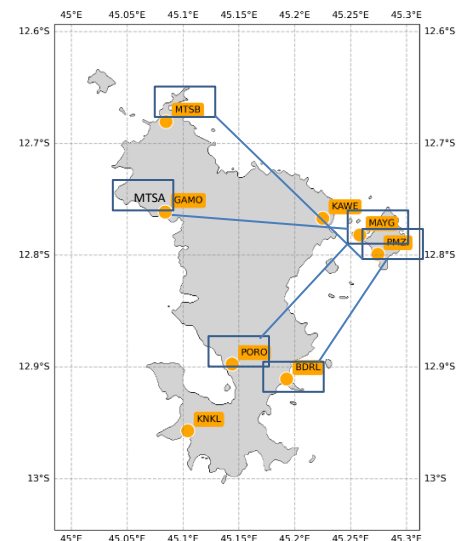
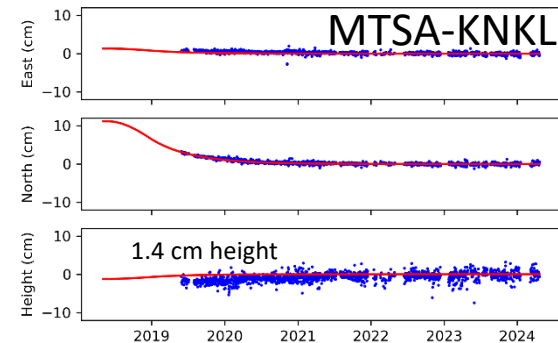
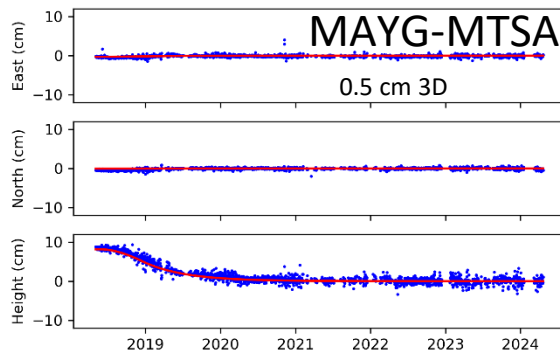
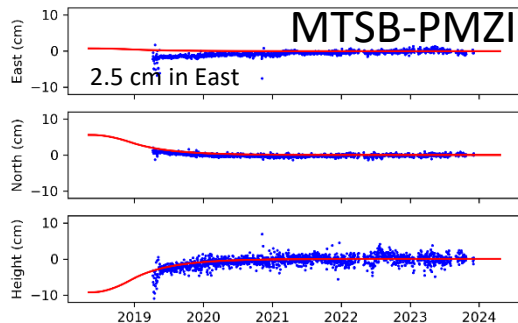
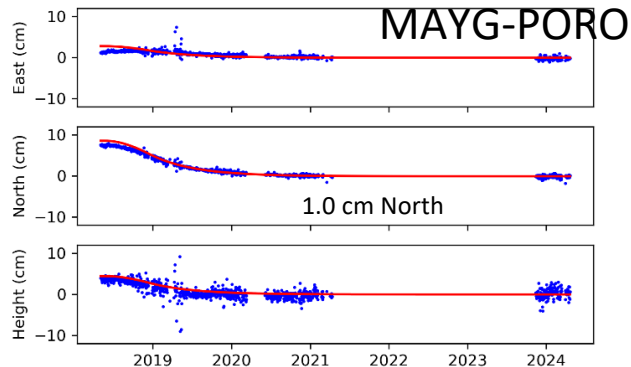
```
$ cct +proj=defmodel +model=path/RGM23_defmod.json coord.txt
```

Model evaluation

Internal deformation

- Comparison with an independant processing at GNSS permanent stations (IGNF, Bernese)

Maximum difference among all possible
baselines in East / North / Up :
2.5 cm/ 1.1 cm/ 2.0 cm



Model evaluation

GNSS: campaign sites

New GNSS observations (campaign sites):

- 2 obs. sessions (2 h) from 11/09/2023 to 04/12/2023
- Stacked coordinates computed in IGS20@2023.75

RGM04 coordinates converted to ITRF2020 and propagated to epoch 2023.75 to compute the 2004-2023.75 displacements.



Fig. 16 common sites

Model evaluation

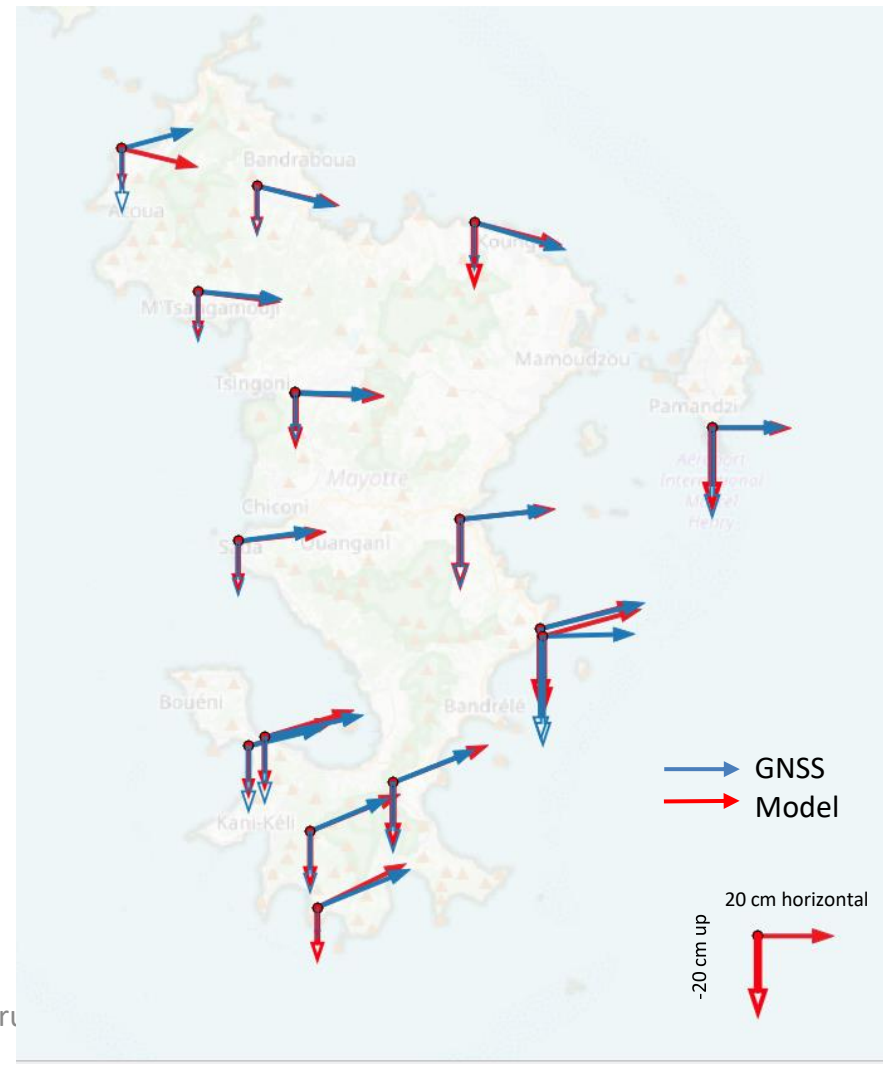
GNSS: campaign sites

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- Stacked coordinates computed in IGS20@2023.75

RGM04 coordinates converted to ITRF2020 and propagated to epoch 2023.75 to compute the 2004-2023.75 displacements.

Fig. Estimated displacements of the 16 common sites



Model evaluation

GNSS: campaign sites

New GNSS observations (campaign sites):

- 2 obs. sessions (2 h) from 11/09/2023 to 04/12/2023
- Stacked coordinates computed in IGS20@2023.75

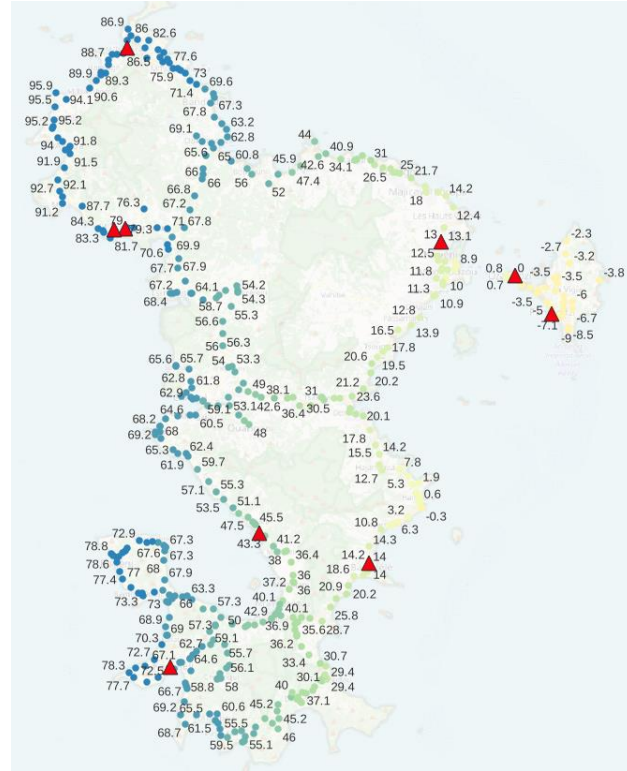
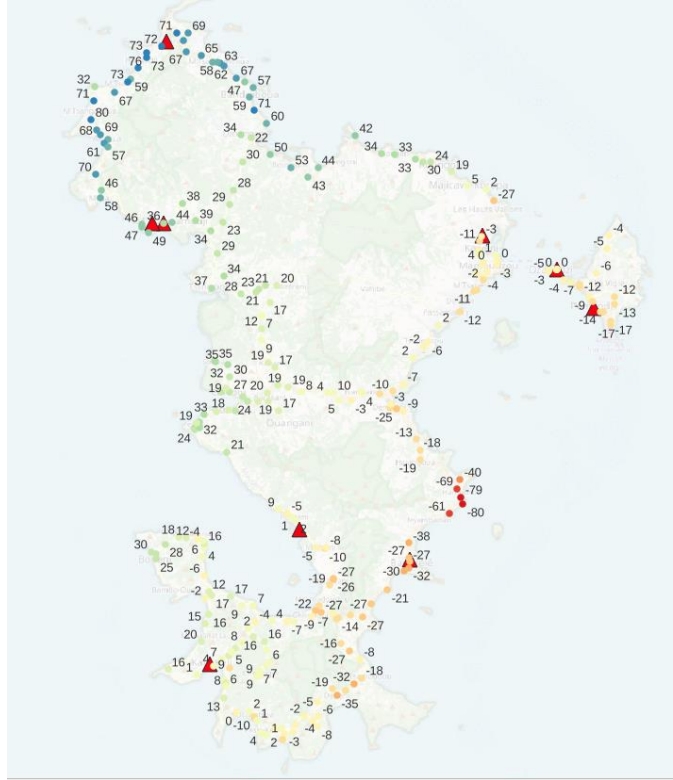
RGM04 coordinates converted to ITRF2020 and propagated to epoch 2023.75 to compute the 2004-2023.75 displacements.

Fig. GNSS displacements minus model



Model evaluation

Levelling



Reference benchmark:
N – 402 - BIS

▲ GNSS permanent stations

Units:
mm

● -80 - -70
● -70 - -60
● -60 - -50
● -50 - -40
● -40 - -30
● -30 - -20
● -20 - -10
● -10 - 0
● 0 - 10
● 10 - 20
● 20 - 30
● 30 - 40
● 40 - 50
● 50 - 60
● 60 - 70
● 70 - 100

Fig. Left) Difference btw levelling campaigns 2006 and 2023. No gravity correction applied. Right) Model prediction.

Model evaluation

Levelling

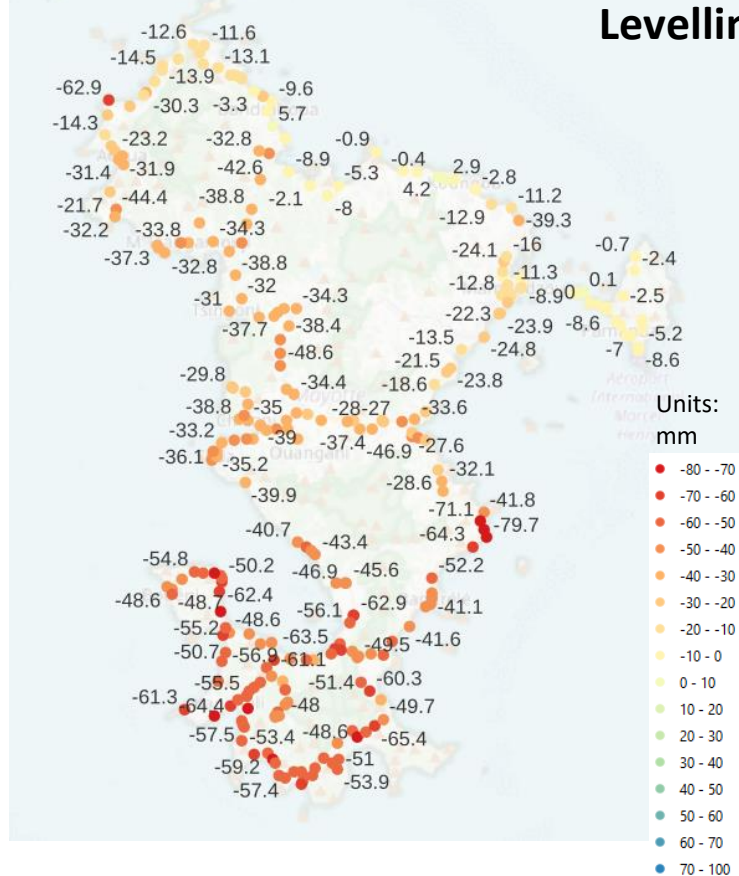
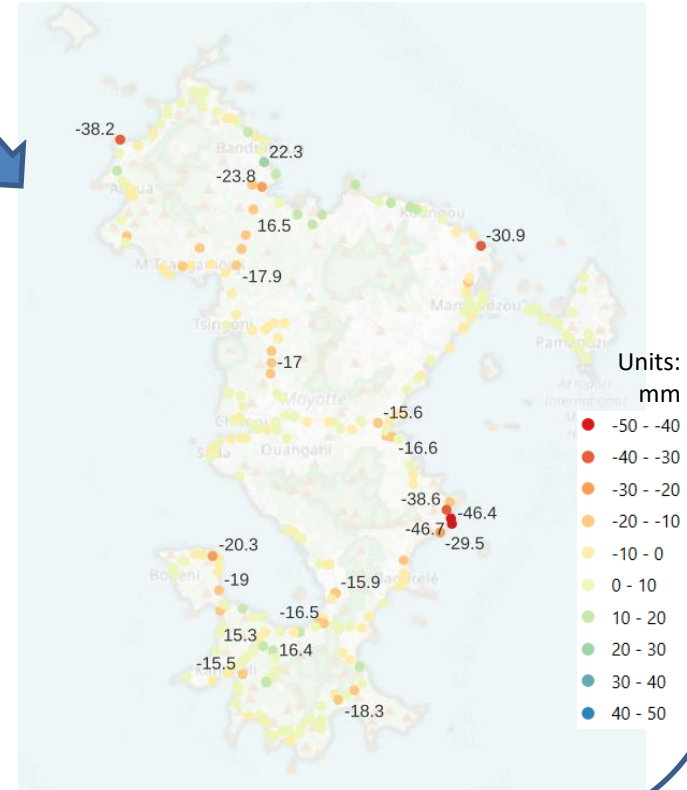
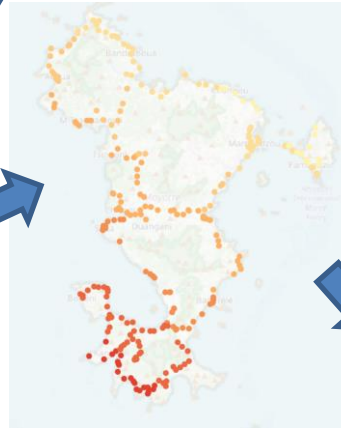


Fig: Levelling (no gravity correction) minus model

Linear model (Fitted in UTM 39 S)

Residual std : 9.7 mm

A (east) (mm/km) : 1.30 +/- 0.10
B (north) (mm/km) : 1.54 +/- 0.06



Perspectives

- Publication of the deformation model and its 'proj' implementation
- Release of the new frame « RGM23 » (by IGN survey department)
- Make use of the deformation model to provide a grid transformation between RGM04 and RGM23?
- Release of a transformation from ITRF2020 @ epoch t to « RGM23 » @ epoch 2023.75 ?
- Upgrade of « RGM23 » to a semi-dynamic frame in a second step ?
Important: no need of the model after 2023.75.
Advantage: All data acquired during the crisis (2018-2020) could be rigourously transformed to RGM23.

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